

A Mini Project Report On

TITLE:

**Vehicle Operating on Compressed Air by Coupling Rod Locomotive and  
Inversion of Slider Crank Mechanism**

Mechanical Engineering

Of

**UNIVERSITY OF MUMBAI**

Submitted by

**HRISHIKESH BHOSALE 201707**

**KEVIN COUTINHO 201712**

**ANISH DALVI 201713**

**Guide**

**PROF. SHAMIM PATHAN**

(Assistant Professor)



**DEPARTMENT OF MECHANICAL ENGINEERING**

**FR. CONCEICAO RODRIGUES INSTITUTE OF TECHNOLOGY, VASHI**

# Vehicle Operating on Compressed Air by Coupling Rod Locomotive and Inversion of Slider Crank Mechanism

**ABSTRACT:** *This paper describes the working of a vehicle which works on pneumatic power. A pneumatic vehicle uses compressed air as a source of energy for locomotion. In this system a double acting pneumatic cylinder is operated as a slider crank mechanism with the help of coupling rod locomotive which converts the linear reciprocation of the cylinder piston rod into oscillatory motion of the driver crank.*

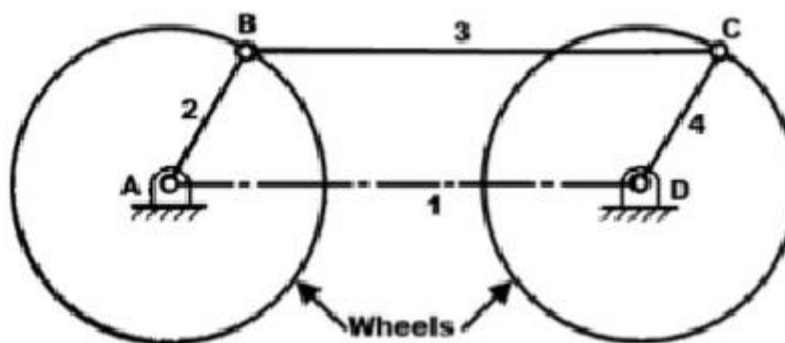
## I. INTRODUCTION

A **coupling rod** or **side rod** connects the driving wheels of a locomotive. Steam locomotives usually have them, but some diesel and electric locomotives, especially older ones and shunters, also have them. The coupling rods transfer the power of drive to all wheels.

A **slider-crank linkage** is a four-link mechanism with three revolute joints and one prismatic, or sliding, joint. **Slider-crank mechanism** is an arrangement of mechanical parts designed to convert straight-line motion to rotary motion, as in a reciprocating piston engine, or to convert rotary motion to straight-line motion, as in a reciprocating piston pump.

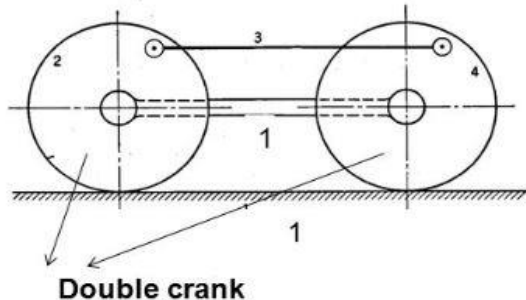
In a pneumatic system, the working fluid is a gas (mostly air) which is compressed above atmospheric pressure to impart pressure energy to the molecules. This stored pressure potential is converted to a suitable mechanical work in an appropriate controlled sequence using control valves and relay module controlled by a microcontroller. In this work a sincere effort is made to develop Vehicle operating on compressed air by **Coupling Rod Locomotive and Inversion of Slider Crank Mechanism**

## II. Coupling Rod Locomotive:



Links -links AD frame (Fixed), link AB (Crank), link BC (Coupling Rod), link CD (Crank)  
 Pairs -Turning Pair = AD (Frame) & AD (Crank), Turning Pair = AD (Frame) & CD (Crank), Turning Pair = AB (Crank) & BC (Connecting Rod), Turning Pair = CD (Crank) & BC (Connecting Rod)

### Inversions of four bar chain Double crank mechanism Coupled wheels of locomotives

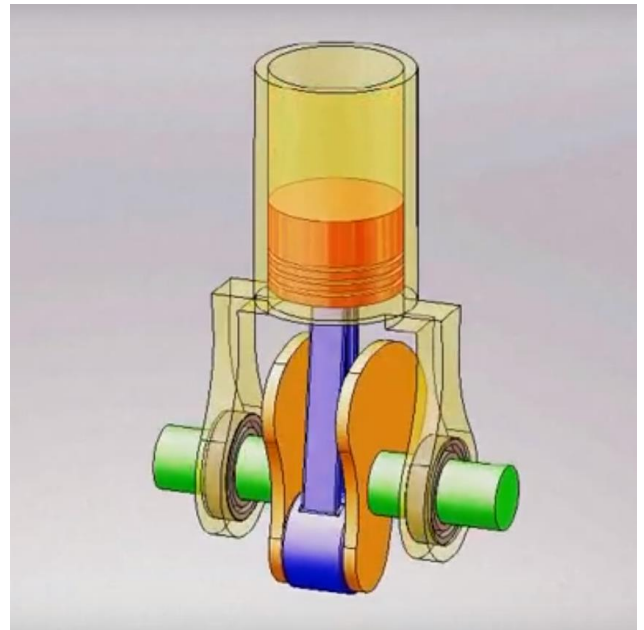
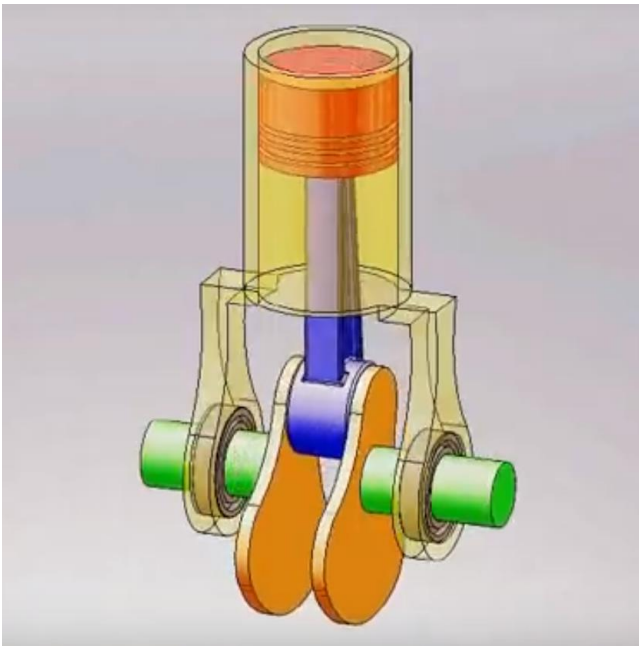
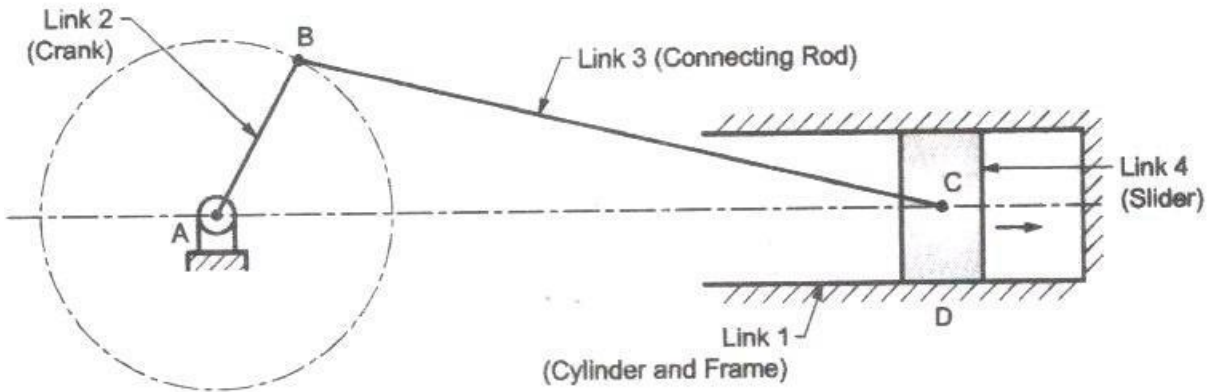


- Consists of four links.
- Link 1 fixed
- Link 2 and 4 are of equal lengths are called as Crank (**Rotating**).
- Link 3 acts as a coupling rod for the two crank (or wheels).
- Rotary motion from one wheel is transferred to other wheel.
- Converts rotary motion from of one crank (or wheel) to rotary motion of other crank (or wheel).
- Egs: Coupled wheels of the locomotives.

**Construction:** This mechanism is an inversion four bar kinematic chain. This has four turning pairs. It is consists of frame AD which is fixed, on which two cranks AC & BD are fitted on it. The cranks are free to rotate about points A and D. Both the cranks have same lengths. Two cranks are connected to each other by means of coupling rod, Connecting the other ends B and C of both cranks. At the connections B and C there is turning pair.

**Working:** When link AB starts rotating about fixed point A. The rotary motion of wheel is transmitted to next wheel by means of coupling rod BC. As a result, the other wheel also starts rotating in same direction and same speed, because both cranks have same radius of rotation.

### III. Inversion of Slider Crank Mechanism:



**Slider-crank chain inversion** arises when the connecting rod, or coupler, of a -crank linkage becomes the ground link, so the slider is connected directly to the crank

Different mechanism by fixing different link of slider crank chain are as follows:

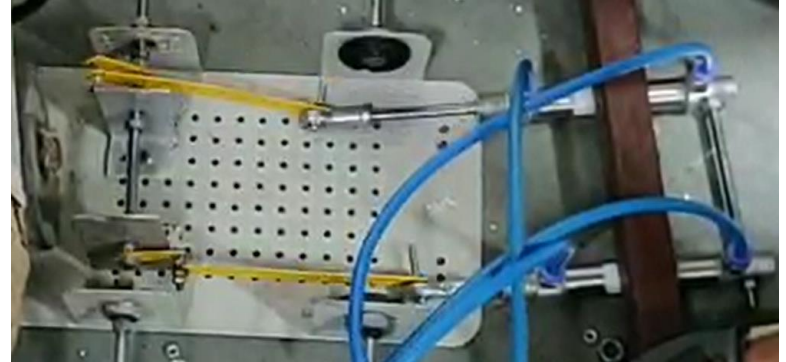
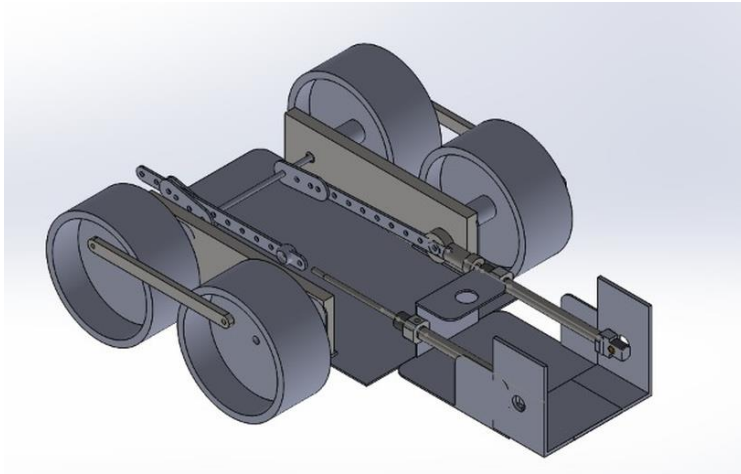
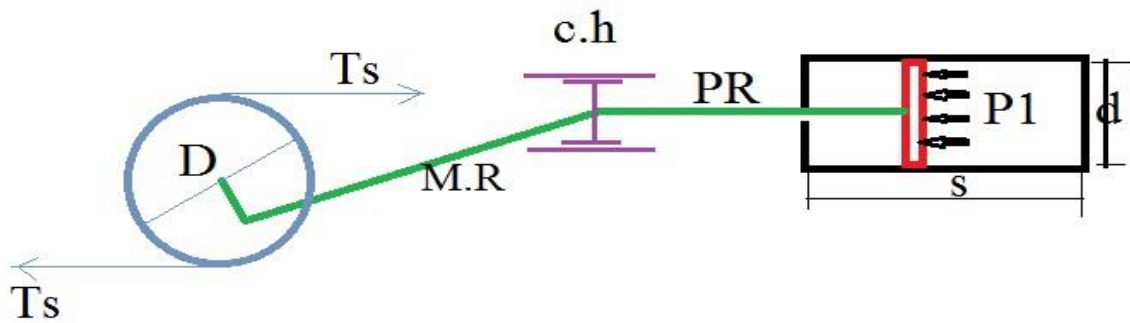
#### **First inversion:**

This inversion is obtained when link 1 (ground body) is fixed.

Application- Reciprocating engine, Reciprocating compressor

### IV: Working and Prototyping of Model

The wheel is connected to the rod by a crank. The rod is connected to the piston rod of the steam cylinder., thereby converting the reciprocating motion of the piston rod generated by steam power into wheel rotation



#### - MATERIALS USED IN CONSTRUCTION OF THE MODEL

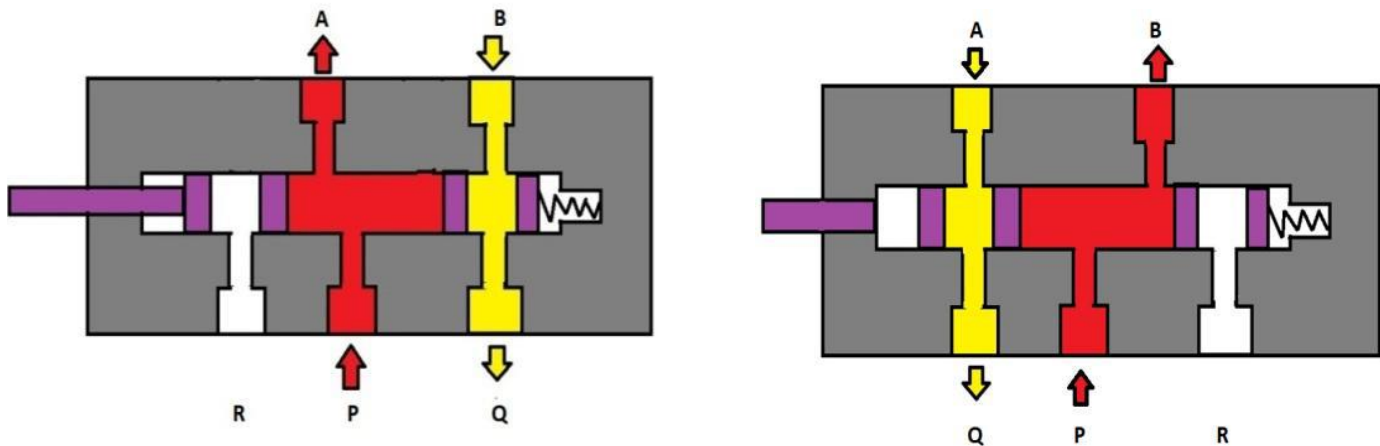
- LONG LINKS	X4
- SHORT LINKS	X4
- SHAFT DIA 13	X3
- BALL BEARINGS	X4
- PNEUMATIC PISTON	X2

#### 4.1. WORKING OF DOUBLE ACTING PNEUMATIC CYLINDER

Pneumatic cylinders or air cylinders are mechanical devices which use the power of compressed air to produce a force in a reciprocating linear motion or cylinders which converts pneumatic power into mechanical power. Compressed air forces the piston to move in the desired direction.

## 4.2 5/2 DIRECTIONAL CONTROL VALVE

To control the to and fro motion of a pneumatic cylinder, the air energy has to be regulated, controlled, and reversed with a predetermined sequence in a pneumatic system. Similarly, one has to control the quantity of pressure and flow rate to generate desired level of force and speed of actuation.



## 4.3 Two Channel Relay Module

This 2 Road/Channel Relay Module (with light coupling) 12V module meet the safety standard as control areas and load area have the isolation groove. Optical coupling isolation module.

### Meaning of High level and Low-level:

High-level trigger refers to using the anode voltage at the VCC connection way of a trigger and triggers the end when the trigger side has the positive voltage or to trigger voltage when the relay is off.

Low-level trigger refers to using the negative voltage at the GND connection way of a trigger and triggers the end when the trigger side has 0 v low voltage or voltage to can trigger, the relay is off.

## 4.4 Arduino UNO

The Arduino UNO is an open-source microcontroller board based on the Microchip ATmega328P microcontroller and developed by Arduino.cc.<sup>[2][3]</sup> The board is equipped with sets of digital and analog input/output (I/O) pins that may be interfaced to various expansion boards (shields) and other circuits.<sup>[1]</sup> The board has 14 Digital pins, 6 Analog pins, and programmable with the Arduino IDE (Integrated Development Environment) via a type B USB cable.

## V. CONCLUSION

The technology of compressed air vehicles is not new. In fact, it has been around for years. Compressed air technology allows engines that are both non-polluting and economical.